



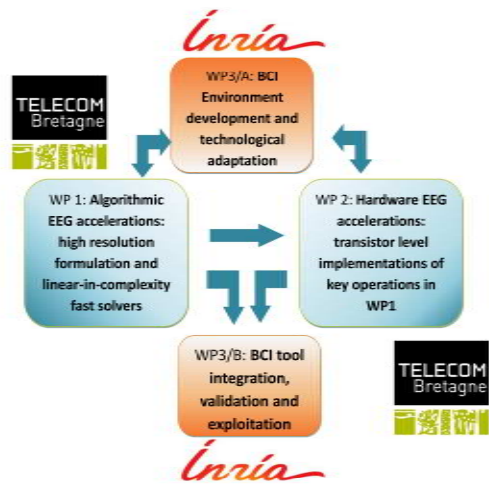
SABRE: Seizing Advances in Bci from high Resolution Eeg imaging in runtime

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General Description

Aim of the project:

Translating computational expensive Epilepsy imaging algorithms in runtime with mutually-inspired techniques in software and hardware acceleration and final integration in the INRIA BCI open source package OpenVibe.



Background

Forward Brain Propagation Models

• Adjoint Double Layer Operator :

$$D^* \varphi = \int_{\partial \Omega} G(r-r') \varphi(r') \partial_n r'$$

• Integral Equation Adjoint Double Layer Formulation

$$\frac{\sigma_j + \sigma_{j+1}}{2(\sigma_{j+1} - \sigma_j)} V_j(r) - \sum_{i=1}^j (\sigma_{i+1} - \sigma_i) D^*(V_i(r)) = \partial_n v_j(r)$$

Standard Discretization and Testing

• Galerkin approach:

$P_i^0 \in H^{-1/2}$ functions for basis and testing :

$$V(r) \approx \sum_{j=1}^N \alpha_j P_j^0$$

$$D_{ij}^* = \langle P_i^0, D^* P_j^0 \rangle \text{ and}$$

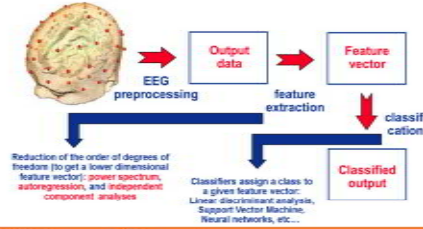
$$I_{ij} = \frac{\sigma_k + \sigma_{k+1}}{2(\sigma_{k+1} - \sigma_k)} \langle P_i^0, P_j^0 \rangle$$

The system equation then writes: $[Z][A] = [\Phi]_j$

with $[Z]_{ij} = -D_{ij}^*$ and $[Z]_{ii} = I_{ij} - D_{ij}^*$

$$[\Phi]_j = \langle P_i^0, \partial_n v_{s,j} \rangle \text{ and } [A]_j = \alpha_j$$

Brain Computer Interface Chain



Achieved Results

Mixed EEG Formulations

Definition Domain of the Integral Operators

• Testing should be done in the dual space of the range of the operator

• In particular D^* is not tested in a correct way : $P_i^0 \in H^{-1/2}$ functions are too irregular

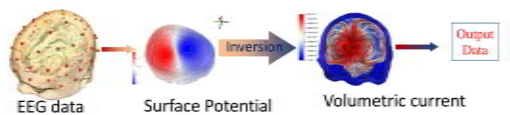
• Use $\tilde{P}_i^1 \in H^{1/2}$, Buffa Christiansen, functions defined on the dual mesh

• New mixed formulations

$$D_{ij}^* = \langle \tilde{P}_i^1, D^* P_j^0 \rangle \text{ and } I_{ij} = \frac{\sigma_k + \sigma_{k+1}}{2(\sigma_{k+1} - \sigma_k)} \langle \tilde{P}_i^1, P_j^0 \rangle$$

$$[Z][A] = [\Phi]_j \text{ with } [\Phi]_j = \langle \tilde{P}_i^1, \partial_n v_{s,j} \rangle$$

The Inverse EEG Problem



Challenges: EEG problem is an ill-posed problem :

- 1) a lack of accuracy in the forward solution will increase the current reconstruction
- 2) a substantial computational cost given that the forward problem has to be solved multiple times
- 3) Building Z: storage complexity $O(N^2)$ and solving the forward problem $O(N^3)$

Achieved Results

Linear-in-complexity algorithmic accelerations

Algorithmic Acceleration

Z is full rank → identify sub-blocks of sparse matrix using octrees

- Octrees give a hierarchical decomposition of the mesh
- Get hierarchical decomposition of Z and interactions list
- Decompose the matrices as :

$$S = S_n + S_f \quad D = D_n + D_f \quad D^* = D_n^* + D_f^*$$

n = near interactions
 Usual way of computation
 Sparse matrix
 Complexity $O(N)$

f = far interacting
 Numerical integration
 Use sparse matrix multiplication

$$S_n = \int_{\partial \Omega} G(r-r') \varphi(r') \partial_n r'$$

$$D_n = \int_{\partial \Omega} \partial_n G(r-r') \varphi(r') \partial_n r'$$

• Use Gaussian integration rules

$$[\mathcal{E}]_{ij} = w_i A_j \text{ complexity } O(N)$$

$$[\Theta]_{ij} = w_i \tilde{P}_i^1(r) A_j \text{ complexity } O(N)$$

• Hierarchical decomposition of G:

$$[W]_{ij} = \begin{cases} \frac{e^{ik|r_i-r_j|}}{|r_i-r_j|} & (1) \text{ for } \int G dr_i \\ 0 & (2) \end{cases}$$

$$[A]_{ij} = \begin{cases} \hat{n}_{r_i} \cdot \nabla \frac{e^{ik|r_i-r_j|}}{|r_i-r_j|} & (1) \text{ for } \int \nabla G dr_i \\ 0 & (2) \end{cases}$$

(1) if the integration points r_i and r_j do not belong to the same smallest partition, (2) otherwise.

$$\rightarrow S = S_n + \mathcal{E}^T W \mathcal{E}, \quad D^* = D_n^* + \mathcal{E}^T \Omega \mathcal{E} \text{ and } D = D^* T$$

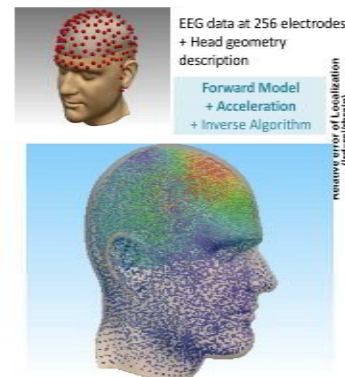
$$\rightarrow \tilde{D}^* = \tilde{D}_n^* + \Theta^T W \mathcal{E} \text{ for the mixed discretization}$$

- Adaptive Cross Algorithm (ACA) for the submatrices,
- Complexity $O(N \log(N))$

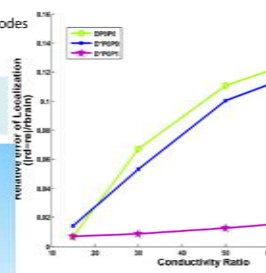
Achieved Results

Validations and performance assessments

• Realistic accelerated source reconstruction

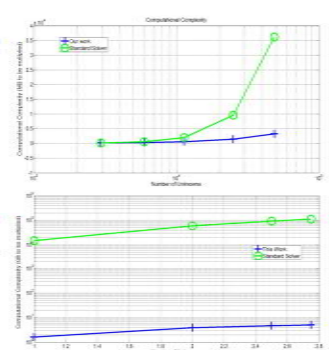


• Highly accurate mixed formulations



• Similar advantages have been observed for the new mixed discretizations when their noise resistance is comparatively assessed

• Efficiency of the Acceleration



On-going and future work

BCI Integration

- Development of specific OpenVibe tools to handle the high number of channels (256) of the available EEG device
- On going experiments to validate the interfacing of the Accelerated EEG brain imaging tools with OpenVibe



Hardware Acceleration

Perform computationally critical operations on a full-custom hardware

• Intel Core i7-5960X: 112GM/s

- Circuit integration:
 - Xilinx Virtex 7 980 T : 2667GM/s
24h → 1h
 - Ad-hoc full-custom circuit (BiCMOS 250nm): 20000GM/s
24h → 8min

